Sixty-sixth Legislative Assembly of North Dakota

FIRST ENGROSSMENT with Senate Amendments ENGROSSED HOUSE BILL NO. 1418

Introduced by

Representative D. Ruby

Senator Rust

- 1 A BILL for an Act to create and enact chapter 8-12 and section 39-01-01.2 of the North Dakota
- 2 Century Code, relating to automated vehicle network companies and autonomous vehicle
- 3 operations.

4 BE IT ENACTED BY THE LEGISLATIVE ASSEMBLY OF NORTH DAKOTA:

5 SECTION 1. Chapter 8-12 of the North Dakota Century Code is created and enacted as

6 follows:

7 <u>8-12-01. Definitions.</u>

8 <u>As used in the chapter:</u>

- 9 <u>1.</u> "Autonomous vehicle" means a vehicle equipped with an automated driving system.
- 10 <u>2.</u> <u>"Client" means a person requesting service from an on-demand autonomous vehicle</u>
- 11 <u>network. The term includes a passenger, a shipper, as defined by section 41-07-02, a</u>
- 12 person entitled under the document, as defined by section 41-07-02, or similar
- 13 <u>individual or commercial enterprise.</u>
- 14 <u>3.</u> <u>"On-demand autonomous vehicle network" means a transportation service network</u>
- 15 <u>that uses a software application or other digital means to dispatch or otherwise enable</u>
- 16 the prearrangement of transportation with autonomous vehicles for purposes of
- 17 <u>transporting persons or goods, including for-hire transportation, transportation for</u>
- 18 <u>compensation, and public transportation.</u>
- 19 <u>8-12-02. General provisions.</u>
- Notwithstanding any other provision of law, a person may operate an on-demand
 autonomous vehicle network. An on-demand autonomous vehicle network may
- 22 provide transportation of persons or goods, including:
- 23 <u>a.</u> <u>For-hire transportation;</u>
- 24 <u>b.</u> <u>Public transportation; and</u>

Sixty-sixth Legislative Assembly

1		<u>C.</u>	Transportation for multiple passengers who agree to share the ride.		
2	<u>2.</u>	An on-demand autonomous vehicle network may connect passengers to autonomous			
3		<u>vehi</u>	icles without human drivers in compliance with subdivision a of subsection 3 of		
4		<u>sect</u>	tion 39-01-01.2 exclusively, or subdivision b of subsection 3 of section 39-01-01.2		
5		<u>as p</u>	part of a digital network that also connects passengers to human drivers who		
6		prov	vide transportation services, consistent with applicable law.		
7	<u>3.</u>	Unless otherwise provided in this chapter and notwithstanding any other provision of			
8		<u>law,</u>	autonomous vehicles and automated driving systems without human drivers are		
9		gove	erned by subsection 3 of section 39-01-01.2.		
10		<u>a.</u>	A state agency or political subdivision may not impose requirements, including		
11			performance standards specific to the operation of an autonomous vehicle or		
12			automated driving systems without human drivers in compliance with		
13			subsection 3 of section 39-01-01.2.		
14		<u>b.</u>	A state or local agency or political subdivision may not impose a tax, fee, or other		
15			requirement specific to the operation of an autonomous vehicle that is in		
16			compliance with subsection 3 of section 39-01-01.2, an automated driving		
17			system, or an on-demand vehicle network. This prohibition does not affect vehicle		
18			registration and titling fees otherwise required by law.		
19	<u>4.</u>	<u>This</u>	s chapter may not be construed to modify, limit, or restrict any statutory provision		
20		affe	cting liability, including chapter 26.1-40, 26.1-41, 28-01.3, 32-03.2, or 39-16.1.		
21	SECTION 2. Section 39-01-01.2 of the North Dakota Century Code is created and enacted				
22	as follow)WS:			
23	39-01-01.2. Autonomous vehicle operations.				
24	<u>1.</u>	<u>As ι</u>	used in this section:		
25		<u>a.</u>	"Automated driving system" means hardware and software collectively capable of		
26			performing the entire dynamic driving task for the vehicle on a sustained basis		
27			when installed on a motor vehicle and engaged regardless of whether it is limited		
28			to a specific operational design domain.		
29		<u>b.</u>	"Autonomous vehicle" means a vehicle equipped with an automated driving		
30			<u>system.</u>		

Sixty-sixth Legislative Assembly

1		<u>C.</u>	"Dynamic driving task" means all of the real-time operational and tactical	
2			functions required to operate a vehicle in on-road traffic within the vehicle's	
3			specific operational design domain, if any, excluding the strategic functions such	
4			as trip scheduling and selection of destinations and waypoints.	
5		<u>d.</u>	"Human driver" means an individual with a valid license to operate a motor	
6			vehicle who manually exercises in-vehicle braking, accelerating, steering, and	
7			transmission gear selection input devices to operate a vehicle.	
8		<u>e.</u>	"Minimal risk condition" means a low-risk operating mode in which an	
9			autonomous vehicle operating without a human driver achieves a reasonably	
10			safe state, such as bringing the vehicle to a complete stop, upon experiencing a	
11			failure of the vehicle's automated driving system that renders the vehicle unable	
12			to perform the entire dynamic driving task.	
13		<u>f.</u>	"Operational design domain" means a description of the specific operating	
14			domain in which an automated driving system is designed to properly operate,	
15			including roadway types, speed range, environmental conditions, and other	
16			domain constraints.	
17	<u>2.</u>	An autonomous vehicle must be capable of operating in compliance with all applicable		
18		federal and state law, except to the extent exempted under applicable federal or state		
19		law	, and may operate on the public highways of this state in full compliance with all	
20		<u>veh</u>	icle registration, title, insurance, and all other applicable requirements under this	
21		<u>title</u>	<u>.</u>	
22	<u>3.</u>	An autonomous vehicle with automated driving systems engaged does not require a		
23		<u>hun</u>	nan driver to operate on the public highway if the autonomous vehicle is capable of	
24		<u>ach</u>	ieving a minimal risk condition in case a system failure occurs which renders the	
25		auto	omated driving system unable to perform the entire dynamic driving task relevant to	
26		<u>the</u>	vehicle's intended operational design domain.	
27	<u>4.</u>	<u>An</u>	individual using an autonomous vehicle is not driving or in actual physical control of	
28		the autonomous vehicle and, therefore, is exempt from licensing requirements if:		
29		<u>a.</u>	The automated driving system is completing the entire dynamic driving task; and	
30		<u>b.</u>	The autonomous vehicle is capable of achieving a minimal risk condition if a	
31			system failure occurs that renders the automated driving system unable to	

Sixty-sixth Legislative Assembly

- 1
 perform the entire dynamic driving task relevant to the vehicle's intended.

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 operational design domain.

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 5.
 This section may not be construed to modify, limit, or restrict any statutory provision.
- 4 <u>affecting liability, including chapter 26.1-40, 26.1-41, 28-01.3, 32-03.2, or 39-16.1.</u>